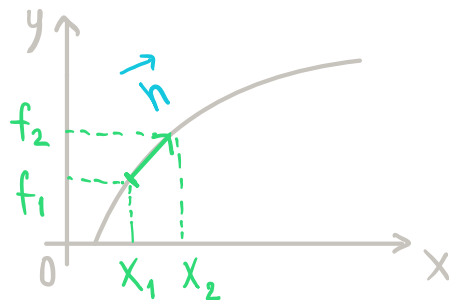


# • TOTÁLNÍ DIFERENCIÁL

- dáno: bod  $C[x_1, y_1]$ ; funkce  $f(x, y)$ ; }  $\nabla f$   
 přírůstek  $\vec{h} (h_x, h_y)$

$$Df(C) = \nabla f \cdot \vec{h} = \frac{\partial f}{\partial x}(C) \cdot h_x + \frac{\partial f}{\partial y}(C) \cdot h_y$$



# • LOKÁLNÍ EXTREMÝ

2D:  $f(x, y)$

$$D^2f(P) = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} \end{pmatrix} \begin{matrix} D_1 \\ D_2 \end{matrix}$$

$\frac{\partial f}{\partial x} = 0$   
 $\frac{\partial f}{\partial y} = 0$  } PODEZŘELÝ BOD  
 $P[x, y]$

$D_N = 0$  ..... nic neříkající  
 $D_2 < 0$  ..... sedlový bod  
 $D_2 > 0$     $D_1 > 0$  ..... lok. minimum  
 $D_2 > 0$     $D_1 < 0$  ..... lok. maximum

3D:  $f(x, y, z)$

$$D^2f(P) = \begin{pmatrix} \frac{\partial^2 f}{\partial x^2} & \frac{\partial^2 f}{\partial x \partial y} & \frac{\partial^2 f}{\partial x \partial z} \\ \frac{\partial^2 f}{\partial y \partial x} & \frac{\partial^2 f}{\partial y^2} & \frac{\partial^2 f}{\partial y \partial z} \\ \frac{\partial^2 f}{\partial z \partial x} & \frac{\partial^2 f}{\partial z \partial y} & \frac{\partial^2 f}{\partial z^2} \end{pmatrix} \begin{matrix} D_1 \\ D_2 \\ D_3 \end{matrix}$$

$\frac{\partial f}{\partial x} = 0$   
 $\frac{\partial f}{\partial y} = 0$   
 $\frac{\partial f}{\partial z} = 0$  } STACIONÁRNÍ BOD  
 $P[x, y, z]$

$D_N = 0$  ..... nic neříkající  
 $D_3 > 0$     $D_2 > 0$     $D_1 > 0$  ..... lok. minimum  
 $D_3 < 0$     $D_2 > 0$     $D_1 < 0$  ..... lok. maximum  
 JINAK ..... sedlový bod